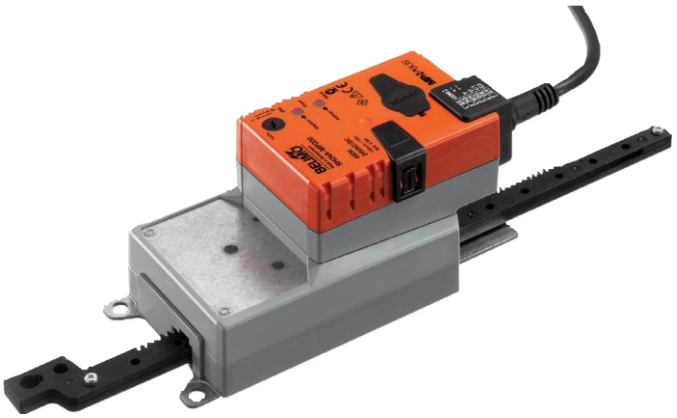
BELIMO

Technical data sheet SH24A-MP100

Communicative linear actuator adjusting dampers and slide valves in technical building installations

- **Air damper size up to approx. 3 m²**
- **Actuating force 450 N**
- **Nominal voltage AC/DC 24 V**
- **Control communicative, modulating DC (0)2...10 V Variable**
- **Position feedback DC 2...10 V Variable**
- **Length of Stroke Max. 100 mm, adjustable in 20 mm increments**
- **Conversion of sensor signals**
- **Communication via Belimo MP-Bus**



MP-BUS

Technical data

Electrical data	Nominal voltage	AC/DC 24 V
	Nominal voltage frequency	50/60 Hz
	Nominal voltage range	AC 19.2...28.8 V / DC 21.6...28.8 V
	Power consumption in operation	3.5 W
	Power consumption in rest position	1.4 W
	Power consumption for wire sizing	6 VA
	Connection supply / control	Cable 1 m, 4 x 0.75 mm²
	Parallel operation	Yes (note the performance data)
Functional data	Actuating force motor	Min. 450 N
	Modifiable actuating force	25%, 50%, 75% reduziert
	Positioning signal Y	DC 0...10 V
	Positioning signal Y note	Input impedance 100 kΩ
	Control signal Y variable	Open-close 3-point (AC only) Modulating (DC 0...32 V)
	Operating range Y	DC 2...10 V
	Operating range Y variable	Start point DC 0.5...30 V End point DC 2.5...32 V
	Position feedback U	DC 2...10 V
	Position feedback U note	Max. 0.5 mA
	Position feedback U variable	Start point DC 0.5...8 V End point DC 2.5...10 V
	Position accuracy	±5%
	Direction of motion motor	Selectable with switch
	Direction of motion note	Y = 0 V: with switch 0 (retracted) / 1 (extended)
	Direction of motion variable	Electronically reversible
	Manual override	With push-button, can be locked
	Length of Stroke	Max. 100 mm, adjustable in 20 mm increments
	Stroke limitation	can be limited on both sides with mechanical end stops
	Running time motor	150 s / 100 mm
	Motor running time variable	150...600 s / 100 mm
	Adaption setting range	manual
	Adaption setting range variable	No action Adaption when switched on Adaption after pushing the gear disengagement button
	Override control	MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50%
	Override control variable	MAX = (MIN + 32%)...100% MIN = 0%...(MAX – 32%) ZS = MIN...MAX
	Sound power level motor	52 dB(A)
Safety	Protection class IEC/EN	III Safety extra-low voltage
	Protection class UL	UL Class 2 Supply
	Degree of protection IEC/EN	IP54
	Degree of protection NEMA/UL	NEMA 2, UL Enclosure Type 2
	EMC	CE according to 2014/30/EU

Technical data

Safety	Certification IEC/EN	IEC/EN 60730-1 and IEC/EN 60730-2-14
	Certification UL	cULus according to UL 60730-1A, UL 60730-2-14 and CAN/CSA E60730-1:02
	Mode of operation	Type 1
	Rated impulse voltage supply / control	0.8 kV
	Control pollution degree	3
	Ambient temperature	-30...50°C
	Non-operating temperature	-40...80°C
	Ambient humidity	95% r.h., non-condensing
	Maintenance	Maintenance-free
Weight	Weight	1.1 kg

Safety notes

- The device must not be used outside the specified field of application, especially not in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea)water, snow, ice, insolation or aggressive gases interfere directly with the actuator and that is ensured that the ambient conditions remain at any time within the thresholds according to the data sheet.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Cables must not be removed from the device.
- The rotary supports and coupling pieces available as accessories must always be used if transverse forces are likely. In addition, the actuator must not be tightly bolted to the application. It must remain movable via the rotary support (refer to «Assembly notes»).
- If the actuator is exposed to severely contaminated ambient air, appropriate precautions must be taken on the system side. Excessive deposits of dust, soot etc. can prevent the gear rod from being extended and retracted correctly.
- If not installed horizontally, the gear disengagement pushbutton may only be actuated when there is no pressure on the gear rod.
- To calculate the actuating force required for air dampers and slide valves, the specifications supplied by the damper manufacturers concerning the cross section, the design, the installation site and the ventilation conditions must be observed.
- If a rotary support and/or coupling piece is used, actuation force losses are to be expected.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.

Product features

Mode of operation

Conventional operation:
The actuator is connected with a standard modulating signal of DC 0...10V and drives to the position defined by the positioning signal. Measuring voltage U serves for the electrical display of the damper position 0...100% and as slave control signal for other actuators.
Operation on the MP-Bus:
The actuator receives its digital positioning signal from the higher level controller via the MP-Bus and drives to the position defined. Connection U serves as communication interface and does not supply an analogue measuring voltage.

Converter for sensors

Connection option for a sensor (passive or active sensor or switching contact). The MP actuator serves as an analogue/digital converter for the transmission of the sensor signal via MP-Bus to the higher level system.

Parameterisable actuators

The factory settings cover the most common applications. Single parameters can be modified with the Belimo Service Tools MFT-P or ZTH EU.

Product features

Simple direct mounting

The actuator can be directly connected with the application using the enclosed screws. The head of the gear rod is connected to the moving part of the ventilating application individually on the mounting side or with the Z-KS1 coupling piece provided for this purpose.

Manual override

Manual override with push-button possible (the gear is disengaged for as long as the button is pressed or remains locked).

Adjustable stroke

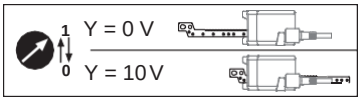
If a stroke limitation will be adjusted, the operating range on this side of the gear rod can be used starting with an extension length of 20 mm and then can be limited respectively in increments of 20 mm by means of the mechanical end stops Z-AS1.

High functional reliability

The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.

Home position

The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out a synchronisation. The synchronisation is in the home position (0%).
The actuator then moves into the position defined by the positioning signal.



Adaption and synchronisation

An adaption can be triggered manually by pressing the “Adaption” button or with the PC-Tool. Both mechanical end stops are detected during the adaption (entire setting range).
Automatic synchronisation after pressing the gearbox disengagement button is configured. The synchronisation is in the home position (0%).
The actuator then moves into the position defined by the positioning signal.
A range of settings can be adapted using the PC-Tool (see MFT-P documentation)

Accessories

Gateways

Description	Type
Gateway MP to Modbus RTU, AC/DC 24 V	UK24MOD
Gateway MP for BACnet MS/TP, AC/DC 24 V	UK24BAC
Gateway MP to LonWorks, AC/DC 24 V, LonMark certified	UK24LON
Gateway MP to KNX, AC/DC 24 V, EIBA certified	UK24EIB

Electrical accessories

Description	Type
Digital position indicator for front-panel mounting, 0...99%, front mass 72 x 72 mm	ZAD24
Range controller for wall mounting, adjustable electron. Min./max. angle of rotation limitation	SBG24
Positioner for wall mounting, range 0...100%	SGA24
Positioner in a conduit box, range 0...100%	SGE24
Positioner for front-panel mounting, range 0...100%	SGF24
Positioner for wall mounting, range 0...100%	CRP24-B1
Connecting cable 5 m, A+B: RJ12 6/6, To ZTH/ZIP-USB-MP	ZK1-GEN
Connection cable 5 m, A: RJ11 6/4, B: Free wire end, To ZTH/ZIP-USB-MP	ZK2-GEN

Mechanical accessories

Description	Type
End stop set for SH	Z-AS1
Rotary support for compensation of transverse forces	Z-DS1
Coupling piece M8 for SH, galvanised steel	Z-KS1

Service Tools

Description	Type
Service Tool, for MF/MP/Modbus/LonWorks actuators and VAV-Controller	ZTH EU
Belimo PC-Tool, software for adjustments and diagnostics	MFT-P
Adapter to Service Tool ZTH	MFT-C

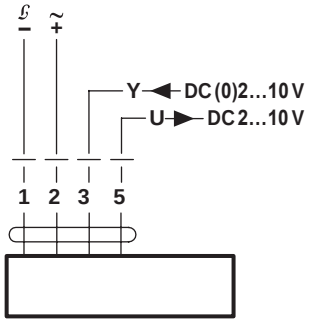
Electrical installation

Notes

- Connection via safety isolating transformer.
- Parallel connection of other actuators possible. Observe the performance data.

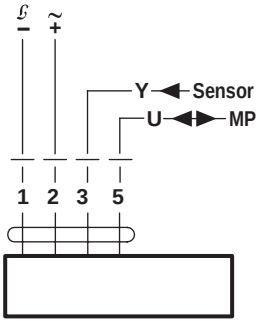
Wiring diagrams

AC/DC 24 V, modulating



Cable colours:
1 = black
2 = red
3 = white
5 = orange

Operation on the MP-Bus



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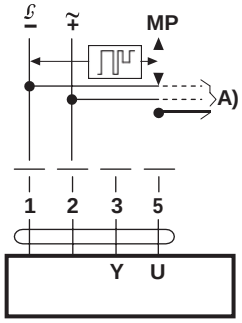
Functions

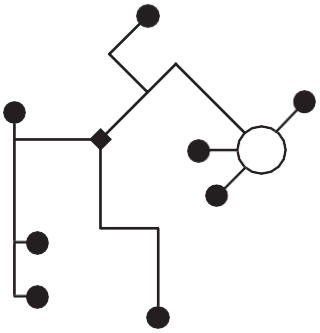
Functions when operated on MP-Bus

Connection on the MP-Bus



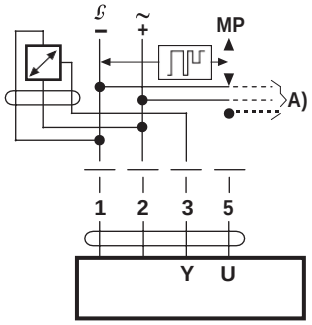
A) more actuators and sensors (max.8)

Network topology



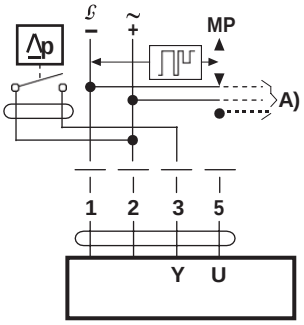
There are no restrictions for the network topology (star, ring, tree or mixed forms are permitted).
Supply and communication in one and the same 3-wire cable
- no shielding or twisting necessary
- no terminating resistors required

Connection of active sensors



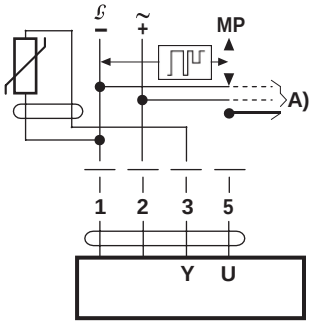
A) more actuators and sensors (max.8)
- Supply AC/DC 24 V
- Output signal DC 0...10 V (max. DC 0...32 V)
- Resolution 30 mV

Connection of external switching contact



A) more actuators and sensors (max.8)
- Switching current 16 mA @ 24 V
- Start point of the operating range must be parameterised on the MP actuator as ≥ 0.5 V

Connection of passive sensors



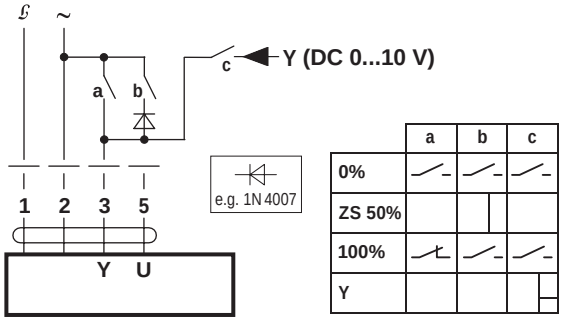
Ni1000	–28...+98°C	850...1600 K 2)
PT1000	–35...+155°C	850...1600 K 2)
NTC	–10...+160°C 1)	200 K...60 kK 2)

A) more actuators and sensors (max.8)
1) Depending on the type
2) Resolution 1 Ohm

Functions

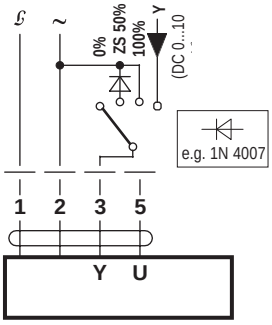
Functions with basic values (conventional mode)

Override control with AC 24 V with relay contacts

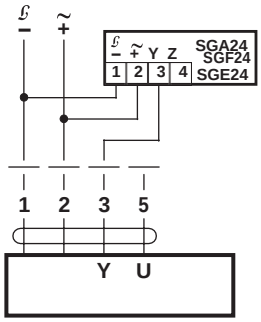


	a	b	c
0%			
ZS 50%			
100%			
Y			

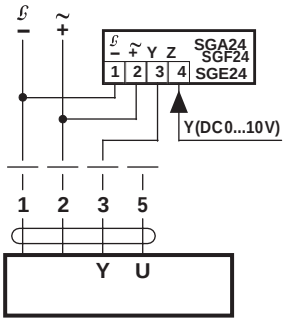
Override control with AC 24 V with rotary switch



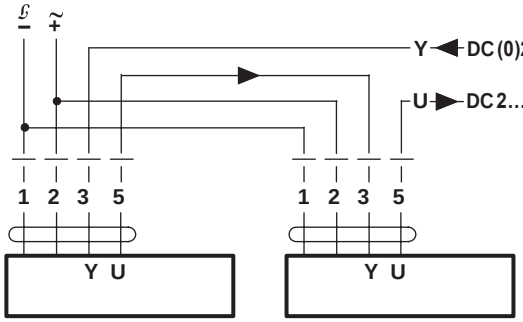
Remote control 0...100% with positioner SG..



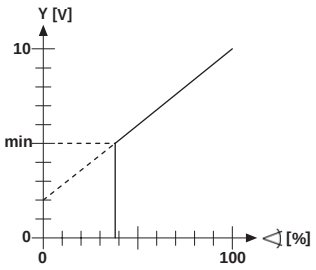
Minimum limit with positioner SG..



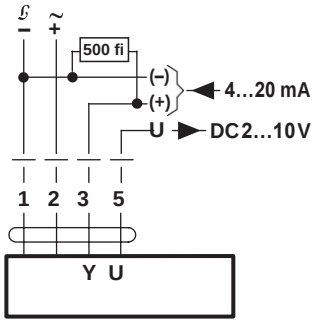
Follow-up control (position-dependent)



Position indication

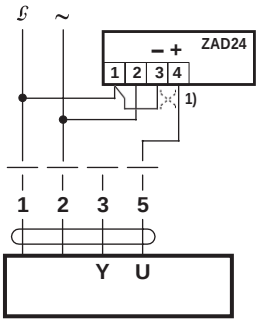


Control with 4...20 mA via external resistor

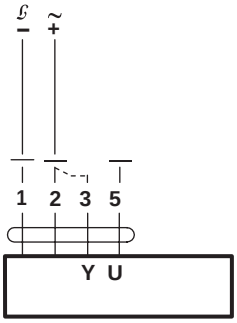


Caution:
The operating range must be set to DC 2...10 V.
The 500 Ω resistor converts the 4...20 mA current signal to a voltage signal DC 2...10 V

Functional check



1) Adapting the direction of stroke

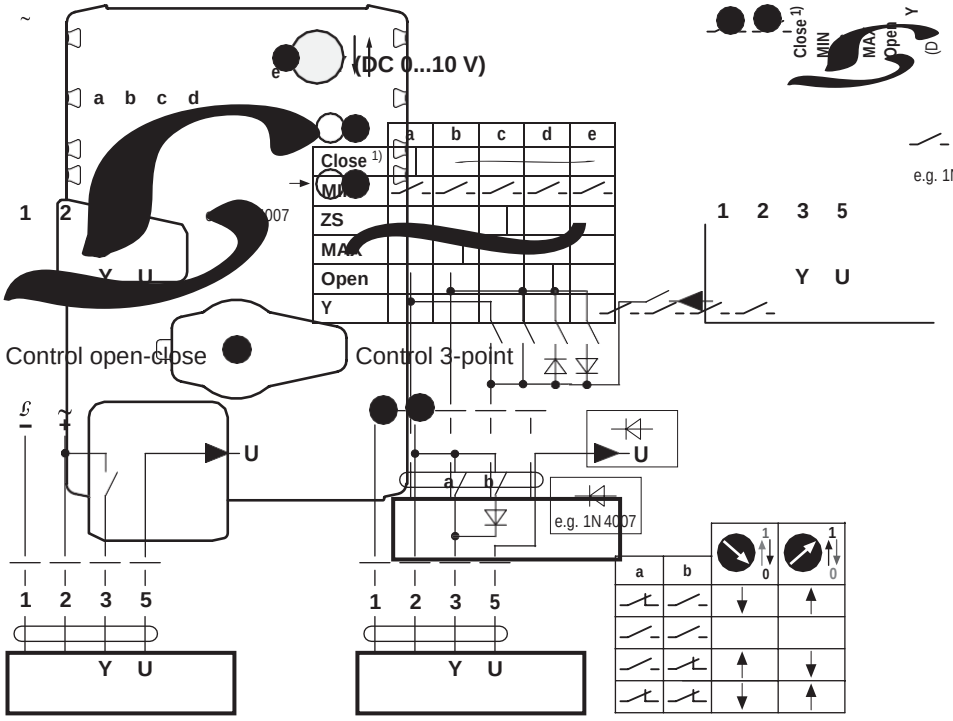


Procedure
1. Apply 24 V to connection 1 and 2
2. Disconnect connection 3:
- for direction of stroke 0: Actuator travels in the direction “retracted”
- for direction of stroke 1: Actuator travels in the direction “extended”
3. Short circuit connections 2 and 3:
- Actuator runs in the opposite direction

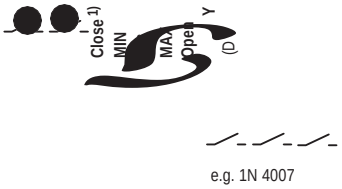
Functions

Functions for actuators with specific parameters (Parametrisation with PC-Tool necessary)

Override control and limiting with AC 24 V with relay contacts



Override control and limiting with AC 24 V with rotary switch



1 2 3 5

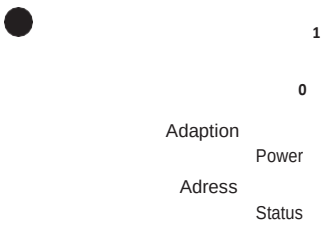
Y U

1) **Caution:** This function is only guaranteed if the start point of the operating range is defined as min. 1.5 V.

Control open-close

Control 3-point

Operating controls and indicators



Direction of stroke switch

Switch over: Direction of stroke changes

Push-button and LED display green

Off: No power supply or malfunction
On: In operation
Press button: Triggers stroke adaptation, followed by standard mode

Push-button and LED display yellow

Off: Standard mode
Flickering: MP communication active
On: Adaptation or synchronising process active
Flashing: Request for addressing from MP master
Press button: Confirmation of the addressing

Gear disengagement button

Press button: Gear disengages, motor stops, manual override possible
Release button: Gear engages, synchronisation starts, followed by standard mode

Service plug

For connecting parameterisation and service tools

Check power supply connection

2 Off and 3 On: Possible wiring error in power supply

Installation notes

Notes

- If a rotary support and/or coupling piece is used, losses in the actuation force losses are to be expected.

Applications without transverse force

The linear actuator is screwed directly to the housing at three points. Afterwards, the head of the gear rod is fastened to the moving part of the ventilation application (e.g. damper or slide valve).

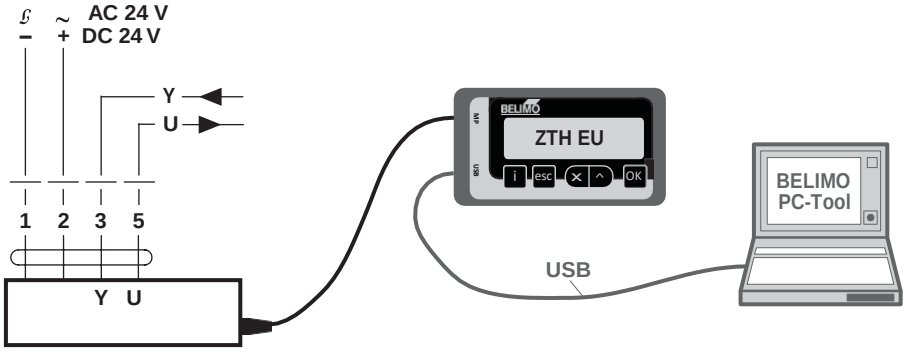
Applications with transverse forces

The coupling piece with the internal thread (Z-KS1) is connected to the head of the gear rod. The rotary support (Z-DS1) is screwed to the ventilation application. Afterwards, the linear actuator is screwed to the previously mounted rotary support with the enclosed screw. Afterwards, the coupling piece, which is mounted to the head of the gear rod, is attached to the moving part of the ventilating application (e.g. damper or slide valve). The transverse forces can be compensated for to a certain limit with the rotary support and/or coupling piece. The maximum permissible swivel angle of the rotary support and coupling piece is 10° (angle), laterally and upwards.

Service

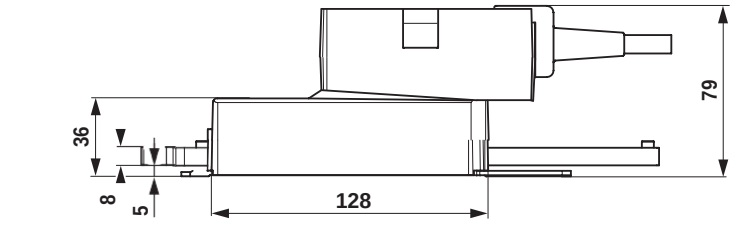
Service Tools connection

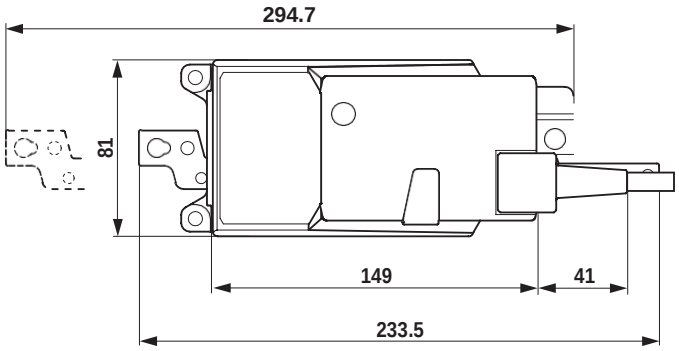
The actuator can be parameterised by ZTH EU via the service socket.
For an extended parameterisation the PC tool can be connected.



Dimensions [mm]

Dimensional drawings





Further documentation

- Overview MP Cooperation Partners
- Tool connections
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